## STEP 2017, P3, Q9 - Solution (2 pages; 14/7/20)

## 1st part

[Note that, because the partices are connected by a spring, rather than an inextensible string, the accelerations of A and B will not be constant, and so suvat cannot be used.]

Applying N2L to A:  $mg - T = m\ddot{y}$ ,

where *T* is the tension in the spring.

Applying N2L to B:  $T = 2m\ddot{x}$ 

Eliminating T,  $mg - 2m\ddot{x} = m\ddot{y}$ ,

so that  $g - 2\ddot{x} = \ddot{y}$ 

Then, integrating wrt *t*:

 $gt - 2\dot{x} = \dot{y} + C$ ; and when t = 0,  $\dot{x} = \dot{y} = 0$ , so that C = 0

And integrating again:

$$\frac{1}{2}gt^2 - 2x = y + D$$
; and when  $t = 0, x = y = 0$ , so that  $D = 0$   
So  $y + 2x = \frac{1}{2}gt^2$ , as required.

## 2nd part

Taking the zero of GPE as being at the top of the table,

the initial total energy is 0 (as the spring is at its natural length).

At time T:

GPE of B is 0

GPE of A is 
$$-mgy(T) = -mg\left(\frac{1}{2}gT^2 - 2x(T)\right)$$

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$$= -mg(\frac{1}{2}g(\frac{6a}{g}) - 2a)$$

$$= -mga$$
KE of B is  $\frac{1}{2}(2m)v^2 = mv^2$ , where  $v$  is the speed to be found  
KE of A is  $\frac{1}{2}m(\dot{y}(T))^2$ ,  
and  $y + 2x = \frac{1}{2}gt^2 \Rightarrow \dot{y} + 2\dot{x} = gt + E$ ;  
and when  $t = 0, \dot{x} = \dot{y} = 0$ , so that  $E = 0$   
Hence  $\dot{y}(T) + 2v = gT$ ,  
and KE of A is  $\frac{1}{2}m(gT - 2v)^2$   
Also, Elastic PE (at time T) is:  $\frac{1}{2}(\frac{\lambda}{a})(y(T) - a)^2$   
and  $y + 2x = \frac{1}{2}gt^2 \Rightarrow y(T) + 2a = \frac{1}{2}g(\frac{6a}{g})$ ,  
so that  $y(T) = a$ , and EPE at time T is 0  
Then (GPE of B)+(GPE of A)+(KE of B)+(KE of A)+EPE = 0,  
so that  $-mga + mv^2 + \frac{1}{2}m(gT - 2v)^2 = 0$ ,  
and  $-2ag + 2v^2 + (g^2T^2 - 4gTv + 4v^2) = 0$   
 $\Rightarrow 6v^2 - 4gTv + g^2(\frac{6a}{g}) - 2ag = 0$   
 $\Rightarrow 3v^2 - 2gTv + 2ag = 0$   
 $\Rightarrow v = \frac{2gT\pm\sqrt{4g^2T^2 - 24ag}}{6}$   
Then  $4g^2T^2 - 24ag = 4g^2(\frac{6a}{g}) - 24ag = 0$ ,

so that  $v = \frac{2g\sqrt{6a/g}}{6} = \sqrt{2ag/3}$ , as required.