

**STEP 2003, Paper 2, Q10 - Solution (5 pages; 7/4/24)**

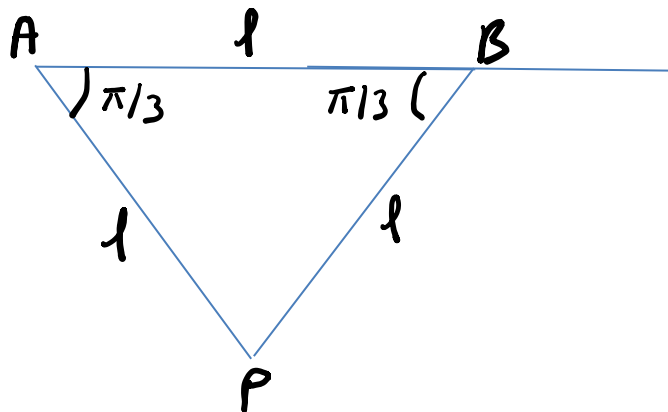
[3 types of method that could, in general, be used to create equations for this type of question are:

- (a) Creating forces diagrams and applying N2L
- (b) Energy method
- (c) Geometrical constraint]

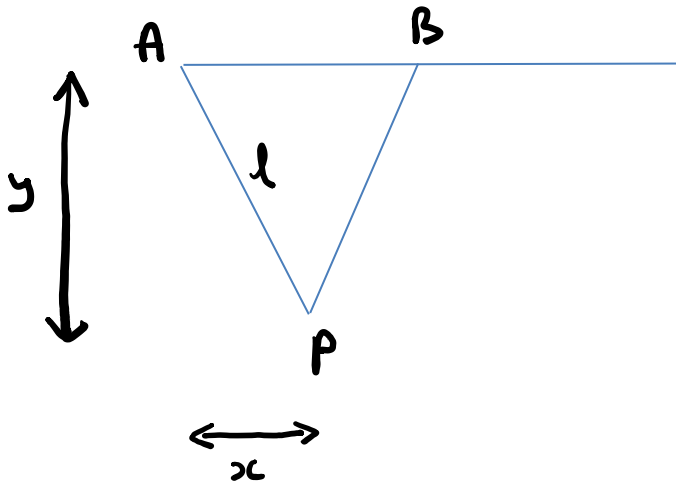
**1<sup>st</sup> Part**

[Here (at least in the 1<sup>st</sup> part of the question), there are unknown forces which prevent the use of methods (a) & (b) (in the case of (b), work will be done by some of the forces).]

Initial position:



Position at a general time:



$$\text{Then } x^2 + y^2 = l^2$$

Differentiating both sides then gives  $2x\dot{x} + 2y\dot{y} = 0$

$$\text{or } x\dot{x} + y\dot{y} = 0$$

$$[\text{where } \dot{x} \equiv \frac{dx}{dt}]$$

And differentiating again gives  $\dot{x}^2 + x\ddot{x} + \dot{y}^2 + y\ddot{y} = 0$  (\*)

Now, the horizontal and vertical displacements of P are

$$\frac{l}{2} - x \text{ (to the left) and } y - l\sin\left(\frac{\pi}{3}\right) \text{ (downwards) (**)}$$

If  $a_x$  and  $a_y$  are the horizontal and vertical displacements of P (at a general time), then differentiating (\*\*) twice,

$$a_x = -\ddot{x} \text{ and } a_y = \ddot{y}$$

Initially the system is at rest, and so  $\dot{x} = \dot{y} = 0$ ;

$$\text{and } a_x = a_1; a_y = a_2$$

$$\text{Also, initially, } x = \frac{l}{2} \text{ and } y = \left(\frac{l}{2}\right)\tan\left(\frac{\pi}{3}\right) = \frac{l\sqrt{3}}{2}$$

Then, from (\*) (initially),

$$0 + \left(\frac{l}{2}\right)(-a_1) + 0 + \left(\frac{l\sqrt{3}}{2}\right)a_2 = 0,$$

so that  $a_1 = \sqrt{3}a_2$ , as required.

### 2<sup>nd</sup> Part

The (horizontal) displacement of B (at a general time) is

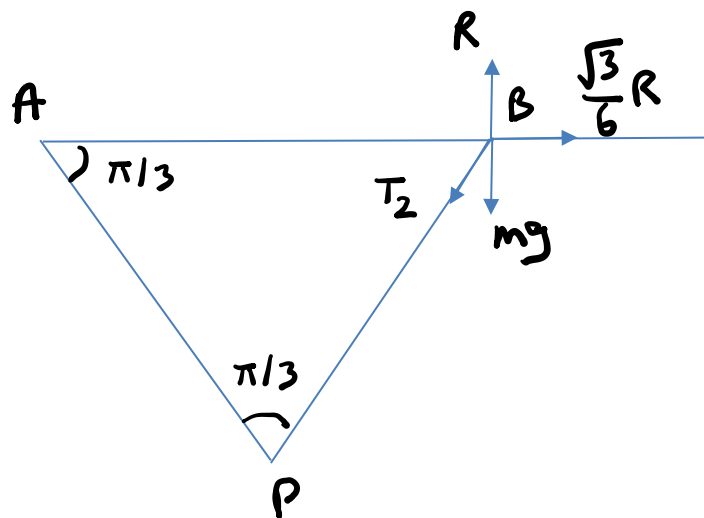
$l - 2x$  (to the left).

Differentiating twice, the acceleration of B is

$$-2\ddot{x} = -2(-a_x) = 2a_x, \text{ and initially this equals } 2a_1$$

### 3<sup>rd</sup> Part

Force diagram for B (in the initial position):



Applying N2L:

$$\text{Vert: } R = mg + T_2 \cos\left(\frac{\pi}{6}\right)$$

$$\text{Horiz: } T_2 \cos\left(\frac{\pi}{3}\right) - \frac{\sqrt{3}}{6} R = m(2a_1)$$

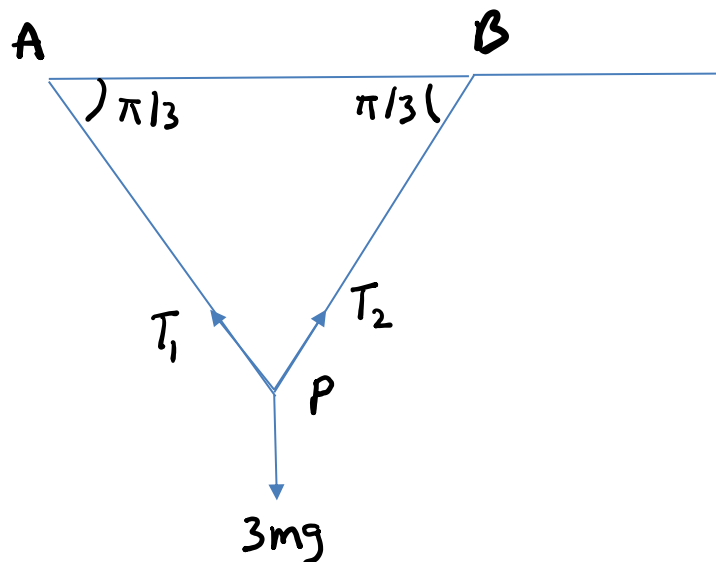
Eliminating  $R$ ,

$$T_2 \cos\left(\frac{\pi}{3}\right) - \frac{\sqrt{3}}{6} (mg + T_2 \cos\left(\frac{\pi}{6}\right)) = m(2a_1)$$

$$\text{so that } T_2 \left(\frac{1}{2} - \frac{\sqrt{3}}{6} \cdot \frac{\sqrt{3}}{2}\right) = m(2a_1 + \frac{\sqrt{3}}{6} g),$$

$$\text{and } T_2 = \frac{m(2a_1 + \frac{\sqrt{3}}{6} g)}{\frac{1}{4}} = \frac{2m}{3} (12a_1 + \sqrt{3} g) \quad (\text{A})$$

Then, for  $P$  (in the initial position):



$$\text{Vert: } 3mg - T_1 \cos\left(\frac{\pi}{6}\right) - T_2 \cos\left(\frac{\pi}{6}\right) = (3m)a_2$$

$$\text{Horiz: } T_1 \cos\left(\frac{\pi}{3}\right) - T_2 \cos\left(\frac{\pi}{3}\right) = (3m)a_1,$$

so that  $T_1 \left(\frac{\sqrt{3}}{2}\right) + T_2 \left(\frac{\sqrt{3}}{2}\right) = 3m(g - a_2)$ , or  $T_1 + T_2 = \frac{6m}{\sqrt{3}}(g - a_2)$

and  $T_1 \left(\frac{1}{2}\right) - T_2 \left(\frac{1}{2}\right) = 3ma_1$ , or  $T_1 - T_2 = 6ma_1$

Then, eliminating  $T_1$ :  $2T_2 = \frac{6m}{\sqrt{3}}(g - a_2 - \sqrt{3} a_1)$ ,

so that  $T_2 = m\sqrt{3}(g - a_2 - \sqrt{3} a_1)$  (B)

Equating (A) and (B) then gives:

$$\frac{2m}{3}(12a_1 + \sqrt{3} g) = m\sqrt{3}(g - a_2 - \sqrt{3} a_1),$$

so that, as  $a_1 = \sqrt{3}a_2$ ,

$$24(\sqrt{3}a_2) + 2\sqrt{3} g = 3\sqrt{3}(g - a_2 - \sqrt{3} (\sqrt{3}a_2))$$

$$\text{or } 24a_2 + 2g = 3(g - 4a_2),$$

giving  $36a_2 = g$ , and so  $a_2 = \frac{g}{36}$

And hence the magnitude of the initial acceleration is:

$$\sqrt{a_1^2 + a_2^2} = \sqrt{3a_2^2 + a_2^2} = 2a_2 = \frac{g}{18}, \text{ as required.}$$